

LAB 1

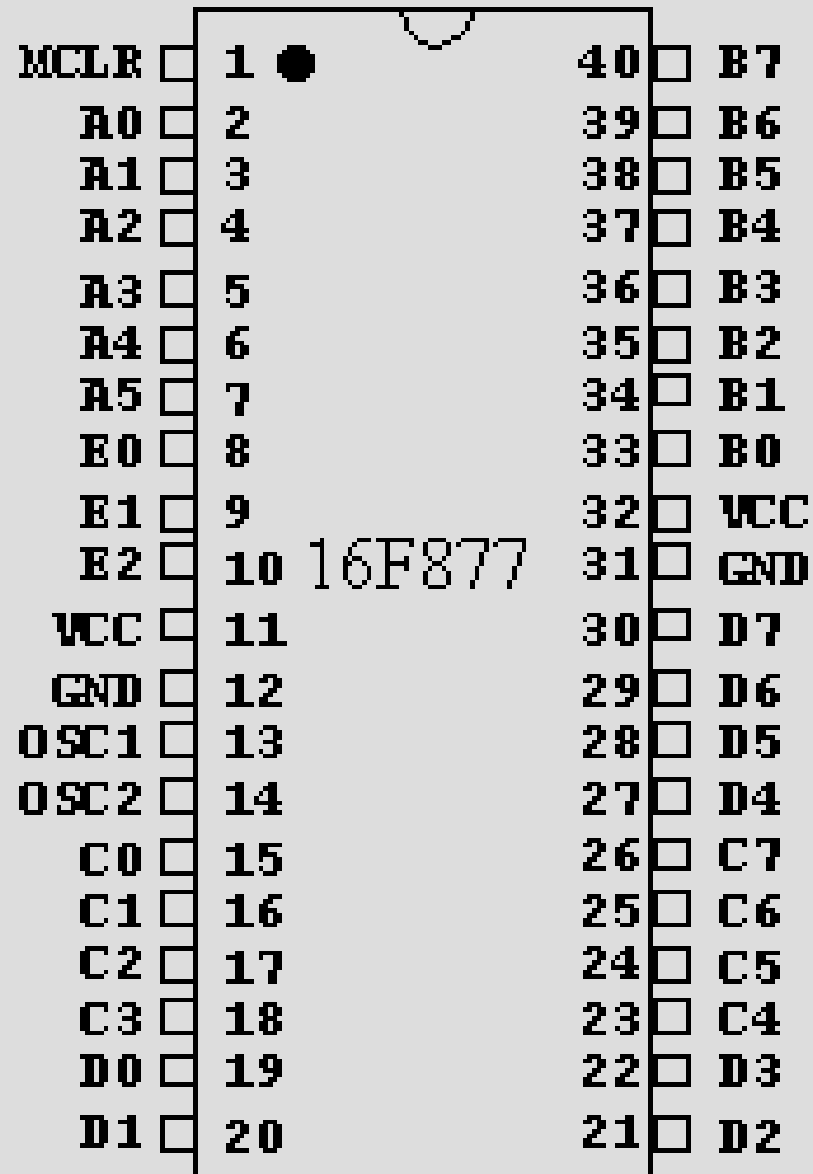
PIC

- ◆ Peripheral Interface Controller.
- ◆ Is a Microcontroller (NOT microprocessor).
- ◆ Is a Family of microcontrollers made by Microchip Technology.
 - PIC10 (10FXXX)
 - PIC12 (PIC12FXXX)
 - PIC16 (16FXXX)
 - PIC 17/18 (18FXXX)
- ◆ Each family has a variety of components along with built in special features(memory sizes and pin packages and different clock ratings ...etc).

PIC 16F877A

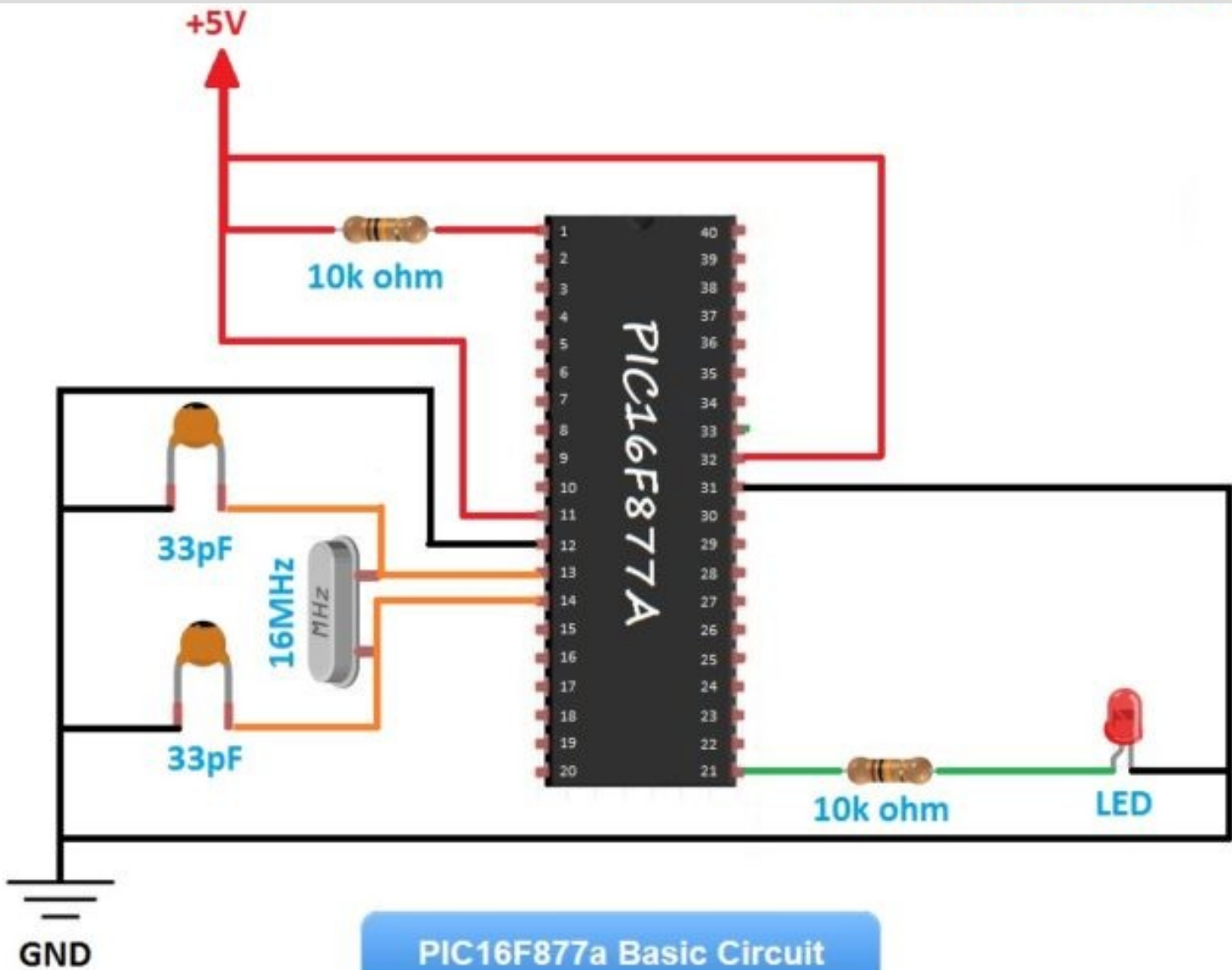
- ◆ 40-pin PIC Microcontroller.
- ◆ It has five Ports on it starting from Port A to Port E





Basic Circuit

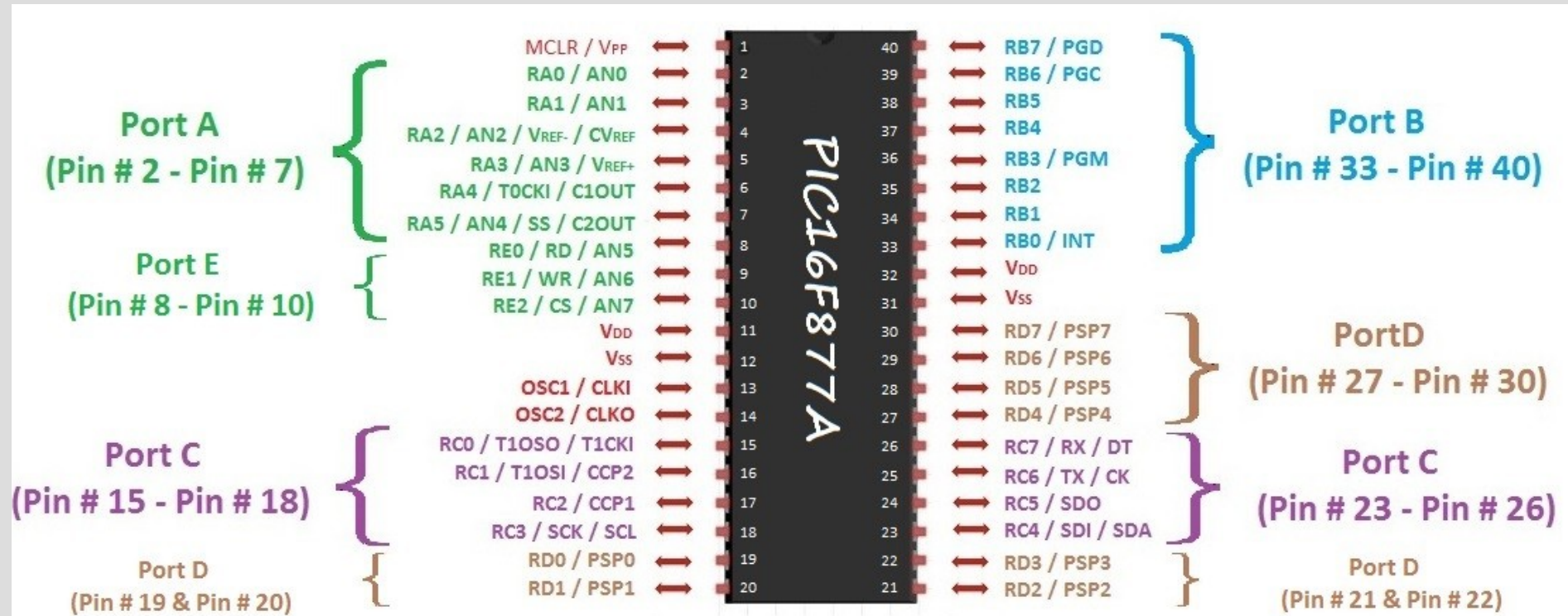
- ◆ Pin #1: MCLR (Master Clear), provide 5V to this pin through a 10k-ohm resistance.
- ◆ Pin #11 & #32: **VDD**, provide it 5V.
- ◆ Pin #12 & #31: **GND**, provided Ground at this pins.
- ◆ Pin #13 & #14: OSC1 (Oscillator 1) and OSC2 (Oscillator 2), attach our Crystal Oscillator at these pins(4MHz to 40MHz).



PIC16F877a Basic Circuit

16F877A Ports

- ◆ PIC16F877a has 5 Ports in total which are:
- ◆ Port A: It has 6 Pins in total starting from Pin #2 to #7, labeled from RA0 to RA5.
- ◆ Port B: It has 8 Pins in total starting from Pin #33 to #40. Port B Pins are labeled from RB0 to RB7.
- ◆ Port C: It has 8 Pins in total. It's pins are not aligned together. First four Pins of Port C are located at Pin # 15 – Pin # 18, while the last four are located at Pin # 23 – Pin # 26.
- ◆ Port D: It has 8 Pins in total, located at Pin #19 – Pin #22, and at Pin #27 – Pin #30.
- ◆ Port E: It has 3 Pins in total starting from Pin #8 to #10, labeled from RE0 to RE2.



PIC16F877A Pin Diagram

Communication Ports

- ◆ Serial communication

- ◆ Pin #25 is acting as TX, sending the serial data.
- ◆ Pin #26 is acting as RX, receiving the serial data.

- ◆ I2C Communication

- ◆ Pin #18: It is acting as SCL, Serial Clock Line.
- ◆ Pin #23: It is acting as SDA,, Serial Data Line.

Input/Output pins

- ◆ Each port has three registers for its operation. These registers are
 - 1) **TRIS** register (data direction register)
 - 2) **PORT** register (read and assign the levels on the pins of the device)

- `TRISB=0;` `//making port as output port (write)`
- `TRISB = 0x00;`
- `TRISB = 0b000000000;`
- `TRISA=1 ;` `//making port as input port (read)`
- `TRISA.F2 = 1;` `// A2 configured as input`
- `TRISB = 0b000000010;` `// All PORTB pins except B1 are configured as`
 `outputs`

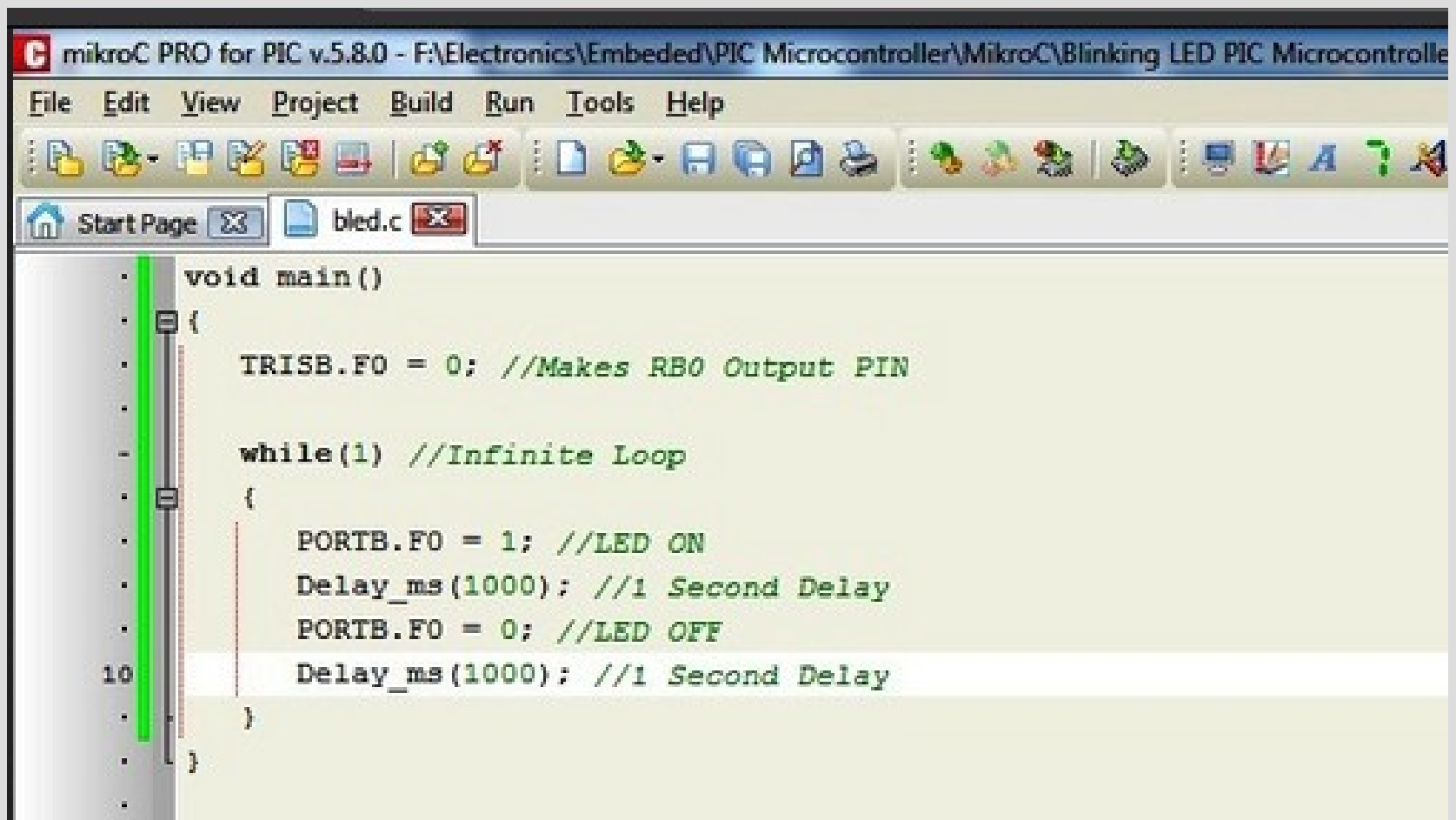
- `TRISA=0` `//making port as output port (write)`
- `PORTA=0x03;` `//Assigning high logic to the RA0 and RA1`

How to Start?

- ◆ **Programming language:** BASIC, C, Pascal ... etc
- ◆ **Compiler:** translate the original BASIC code into HEX code that can be fed to microcontroller(**Mickro c**).
- ◆ **Programmer:** to transfer our HEX files from computer to
microcontroller memory

Example: Blinking LED

◆MikroC

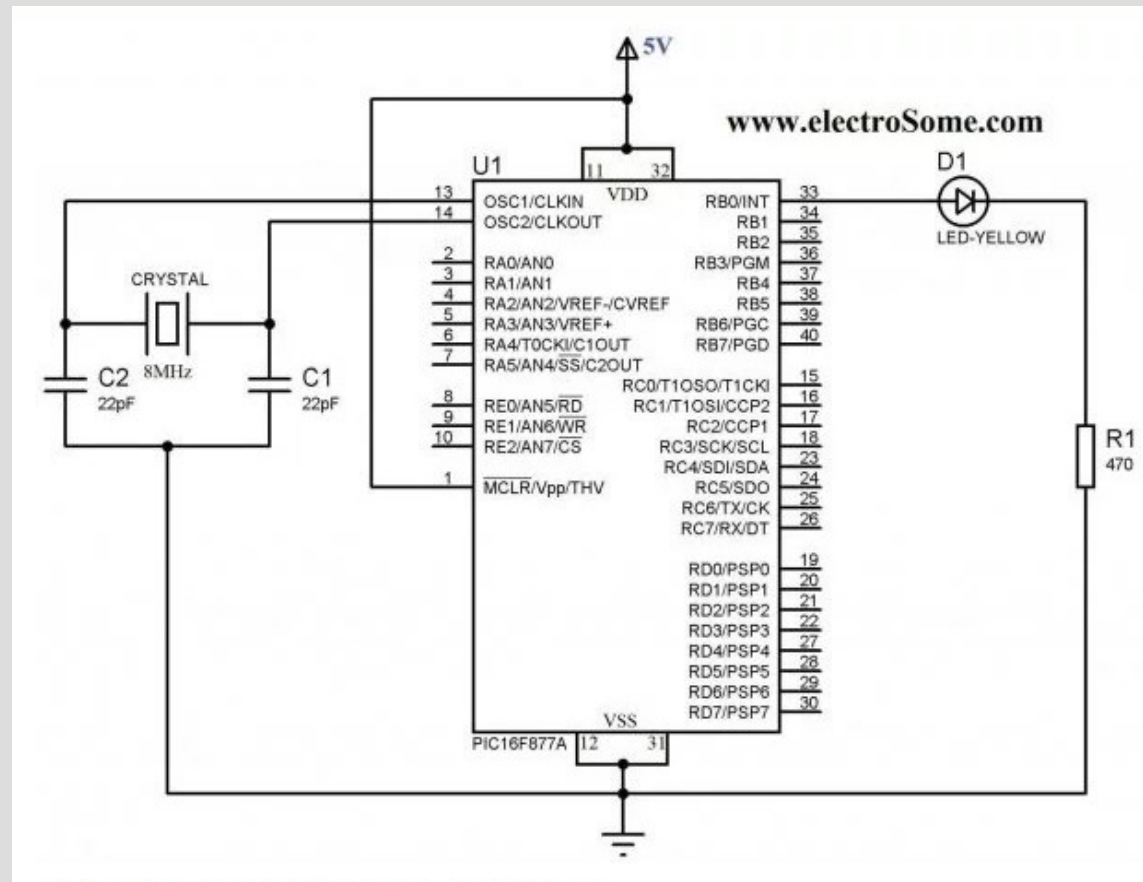


The screenshot shows the MikroC PRO for PIC v.5.8.0 IDE. The title bar indicates the project path: F:\Electronics\Embedded\PIC Microcontroller\MikroC\Blinking LED PIC Microcontrolle. The menu bar includes File, Edit, View, Project, Build, Run, Tools, and Help. The toolbar contains various icons for file operations, compilation, and execution. The main editor window displays a C program named bled.c. The code is as follows:

```
void main()  
{  
    TRISB.F0 = 0; //Makes RB0 Output PIN  
  
    while(1) //Infinite Loop  
    {  
        PORTB.F0 = 1; //LED ON  
        Delay_ms(1000); //1 Second Delay  
        PORTB.F0 = 0; //LED OFF  
        Delay_ms(1000); //1 Second Delay  
    }  
}
```

Example: Blinking LED

◆ Proteus





1. Blinking Led.
2. Traffic Light System.
3. Led controlled bu push button